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1.		

L Number   Hits   Search Text   95   180/197 and yaw and clutch   USPAT; US-PGPUB; EPC; JPC; DERWENT   US-PGPUB; EPC; JPC; DERWENT   US-PGPUB; EPC; JPC; DERWENT   US-PGPUB; EPC; JPC; DERWENT   USPAT; US-PGPUB; EPC; JPC; DERWENT   U	0:55 0:57 0:57 0:57
2 46 180/197 and yaw and clutch and axle USPAT; US-PGPUB; EPG; JPG; DERWENT USPAT; US-	0:57 0:57 0:57
2 46 180/197 and yaw and clutch and axle USPAT; USPAGUB; EPO; JPO; DERWENT USPAGUB; EPO; JPO; DERWEN	0:57 0:57 0:57
2 46 180/197 and yaw and clutch and axle USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-	0:57 0:57 0:57
US-PGPUB; EPO; JPO; DERWENT	0:57 0:57 0:57
Sep	0:57 0:57 0:58
39   180/248 and yaw and clutch and axle   DERWENT   USPAT; US-PGPUB; EPO; JPO; JPO; DERWENT   USPAT; US-PGPUB; EPO; JPO; DERWENT   USPAT; US-PGPUB; EPO; JPO; JPO; DERWENT   USPAT; US-PGPUB; EPO; JPO; JPO; DERWENT   USPAT; US-PGPUB; EPO; JPO; DERWENT   USPAT; US-PGPUB	0:57 0:57 0:58
39	0:57 0:57 0:58
US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO;	0:57 0:58
DERWENT   USPAT;   USPAT;   USPGUB;   EPO; JPO;   DERWENT   USPAT;   USPGUB;   EPO; JPO;   DERWENT   USPAT;   USPGUB;   EPO; JPO;   DERWENT   USPAT;   USPAT;   USPAT;   USPGUB;   EPO; JPO;   DERWENT   USPAT;	0:57 0:58
4 28 180/233 and yaw and clutch and axle  USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; 2004/09/19 2  16 701/67-69.ccls. and yaw and clutch and axle USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO;	0:57 0:58
S-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; USPAT; USPAT; USPAT; USPAT; USPAT; USPAT; USPAT; U	0:57 0:58
EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT US-	0:58
DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT US-PGPUB; EPO;	0:58
180/345 and yaw and clutch and axle	0:58
16	0:58
DERWENT USPAT; US-PGPUB; EPO; JPO;	
16 701/67-69.ccls. and yaw and clutch and axle USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB;	
axle	
To and yaw and clutch and axle  EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO;	0.50
7 0 701/89. and yaw and clutch and axle USPAT; USPA	0.50
7 0 701/89. and yaw and clutch and axle USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO;	0.50
US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO;	ひょうと
8 15 701/89 and yaw and clutch and axle USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO;	
8 15 701/89 and yaw and clutch and axle USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DEPO; JPO; USPAT; US-PGPUB; EPO; JPO;	
US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT US-PGPUB; EPO; JPO;	
9 10 701/82 and yaw and clutch and axle	0:59
DERWENT USPAT; US-PGPUB; EPO; JPO; US-PGPUB; EPO; JPO;	
9 10 701/82 and yaw and clutch and axle USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DSPAT; US-PGPUB; EPO; JPO;	
US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO;	n - 5 a
EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO;	0.33
10 4 701/87 and yaw and clutch and axle USPAT; US-PGPUB; EPO; JPO; 2004/09/19 2	
US-PGPUB; EPO; JPO;	
EPO; JPO;	1:00
11 0 192/54.1 and yaw and clutch and axle USPAT; 2004/09/19 2	1 • 00
US-PGPUB;	1.00
EPO; JPO;	
DERWENT	
1 192/54.1 and yaw and clutch USPAT; 2004/09/19 2	1:00
US-PGPUB;	
EPO; JPO;	
DERWENT USPAT; 2004/09/19 2	1:01
clutch US-PGPUB;	±. VI
EPO; JPO;	
DERWENT	
- 3 180/6.2 and oversteer and understeer and USPAT; 2004/09/19 1	7:04
yaw and "yaw rate sensor" US-PGPUB;	
EPO; JPO;	
DERWENT USPAT; 2004/08/17 1	8 · O1
understeer and yaw and "yaw rate sensor" US-PGPUB;	J.VI
EPO; JPO;	
DERWENT	
- 1 microprocessor and oversteer and USPAT; 2004/08/17 1	
understeer and yaw and "yaw rate sensor" US-PGPUB;	8:02
and axle and clutch   EPO; JPO;   DERWENT	8:02
- 1 microprocessor and oversteer and USPAT; 2004/08/17 1	8:02
understeer and yaw and "rate sensor" and US-PGPUB;	
axle and clutch EPO; JPO;	
DERWENT	

-	10	oversteer and understeer and yaw and "rate sensor" and axle and clutch	USPAT; US-PGPUB; EPO; JPO;	2004/08/17 18:03	
			DERWENT		
-	10		USPAT;	2004/08/17 18:03	
		sensor" and axle and clutch and speed	US-PGPUB; EPO; JPO;		
			DERWENT		
_	1	701/67 and oversteer and understeer and	USPAT;	2004/09/16 14:45	
		yaw and "yaw rate" and sensor	US-PGPUB;		
			EPO; JPO; DERWENT		
_	137	701/\$.ccls. and oversteer and understeer	USPAT;	2004/09/16 14:45	
		and yaw and "yaw rate" and sensor	US-PGPUB;	2001/05/10 11.45	
			EPO; JPO;		
			DERWENT		
-	21		USPAT;	2004/09/16 14:45	
1		and yaw and "yaw rate" and sensor and	US-PGPUB;		
		Clucch	EPO; JPO; DERWENT		
<del>-</del>	0	701/\$.ccls. and oversteer and understeer	USPAT;	2004/09/16 14:45	
		and yaw and "yaw rate" and sensor and	US-PGPUB;		
		clutch and pwm and pid	EPO; JPO;		
		701 (0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	DERWENT	0004/00/26 24 46	
-	0	701/\$.ccls. and oversteer and understeer and yaw and "yaw rate" and sensor and	USPAT; US-PGPUB;	2004/09/16 14:46	
		clutch and pid	EPO; JPO;		
	,		DERWENT		
-	0		USPAT;	2004/09/16 14:46	
		and yaw and "yaw rate" and sensor and	US-PGPUB;		
		clutch and (porportional and integral and	EPO; JPO;		
1_	1	derivative)   701/\$.ccls. and oversteer and understeer	DERWENT USPAT;	2004/09/16 14:50	
	1	and yaw and "yaw rate" and sensor and	US-PGPUB;	2004/05/10 14.50	
		clutch and (proportional and integral and	EPO; JPO;		
		derivative)	DERWENT		
-	17	701/\$.ccls. and oversteer and understeer	USPAT;	2004/09/16 14:48	
		and yaw and "yaw rate" and sensor and clutch and proportional	US-PGPUB; EPO; JPO;		
		Clutch and proportional	DERWENT		
-	3		USPAT;	2004/09/16 14:50	
		sensor and clutch and (proportional and	US-PGPUB;		
		integral and derivative)	EPO; JPO; DERWENT		
_	2	oversteer and understeer and yaw and "yaw	USPAT;	2004/09/16 14:52	
	_	rate" and sensor and clutch and	US-PGPUB;	2001,03,10 11.02	
1		(proportional and integral and derivative)	EPO; JPO;		
		( )	DERWENT	0004/00/25 22 22	
-	4	(angle WITH steering) and yaw and "yaw rate" and sensor and clutch and	USPAT;	2004/09/16 14:51	-
İ		(proportional and integral and derivative)	US-PGPUB; EPO; JPO;		
		, FIFTHERMAN AND INCOME AND ADDITIONAL ADDITIONAL AND ADDITIONAL ADDITIONAL AND ADDITIONAL ADDI	DERWENT		
-	35		USPAT;	2004/09/16 14:54	
		rate" and sensor and clutch	US-PGPUB;		
			EPO; JPO;		
-	28	("1013333" "2018923" "2456681" "2782547" "3.	DERWENT 5563PA5"   "381	   2084/0 <b>9</b> 0681324584	467548
-	54		USPAT;	2004/09/16 16:45	]
İ	İ	acceleration" and "yaw rate" and	US-PGPUB;		
		microprocessor	EPO; JPO;		
_	2	understeer and oversteer and "lateral	DERWENT	2004/00/16 16:46	
_	-	acceleration" and "yaw rate" and	USPAT; US-PGPUB;	2004/09/16 16:46	
		microprocessor and sensor\$3 and clutch and	EPO; JPO;		
1		axle	DERWENT		
-	7		USPAT;	2004/09/16 16:47	
	-	microprocessor and sensor\$3 and clutch and axle	US-PGPUB;		
		avie	EPO; JPO; DERWENT		
<u> </u>	I	I	PHIMPIAI		J

-	8		USPAT;	2004/09/16 16:53
		microprocessor and sensor\$3 and clutch and	US-PGPUB;	
		axle	EPO; JPO;	
			DERWENT	
-	17	"5332059"	USPAT;	2004/09/16 16:52
			US-PGPUB;	
			EPO; JPO;	
			DERWENT	
-	49	"lateral acceleration" and yaw and slip	USPAT;	2004/09/16 16:53
1		and sensor\$3 and clutch and axle	US-PGPUB;	
			EPO; JPO;	
}			DERWENT	
-	6	"5742917" and oversteer and understeer and	USPAT;	2004/09/19 17:29
•		yaw and "yaw rate sensor"	US-PGPUB;	
			EPO; JPO;	
			DERWENT	
-	4	6,131,054	USPAT;	2004/09/19 17:46
			US-PGPUB;	
	i		EPO; JPO;	
			DERWENT	
-	304	"ball ramp" and actuator and clutch	USPAT;	2004/09/19 17:47
	ļ	·	US-PGPUB;	
			EPO; JPO;	
			DERWENT	
<del>-</del>	132	("ball ramp" and actuator and clutch) and	USPAT;	2004/09/19 17:50
		spline	US-PGPUB;	
			EPO; JPO;	
]		/#4535100#   #4030110#   #4034013#	DERWENT	
-	14	("4735108"   "4838119"   "4934213"	USPAT	2004/09/19 17:48
		"5069305"   "5083986"   "5699888"		
		"5749801"   "5845546"   "5884738"		
		"5910064"   "6098770"   "6461267"		
	-	"6533090"   "6578654").PN.	IICDAM.	2004/00/10 10:52
-	l '	("ball ramp" and actuator and clutch) and	USPAT;	2004/09/19 18:53
1		spline and yaw	US-PGPUB;	
	İ		EPO; JPO;	
l _	,	   "proportional integral derivative	DERWENT	2004/09/19 19:01
-	2	controller" and yaw and clutch	USPAT;	2004/09/19 19:01
i		Controller and yaw and clutch	US-PGPUB;	
			EPO; JPO; DERWENT	
l _	,	   "proportional integral derivative" and yaw	USPAT;	2004/09/19 20:53
_	1 ′	and clutch	US-PGPUB;	2004/09/19 20:53
		and Crutch	EPO; JPO;	
			DERWENT	
L	<u>L</u>	I	DEKMENT	1